

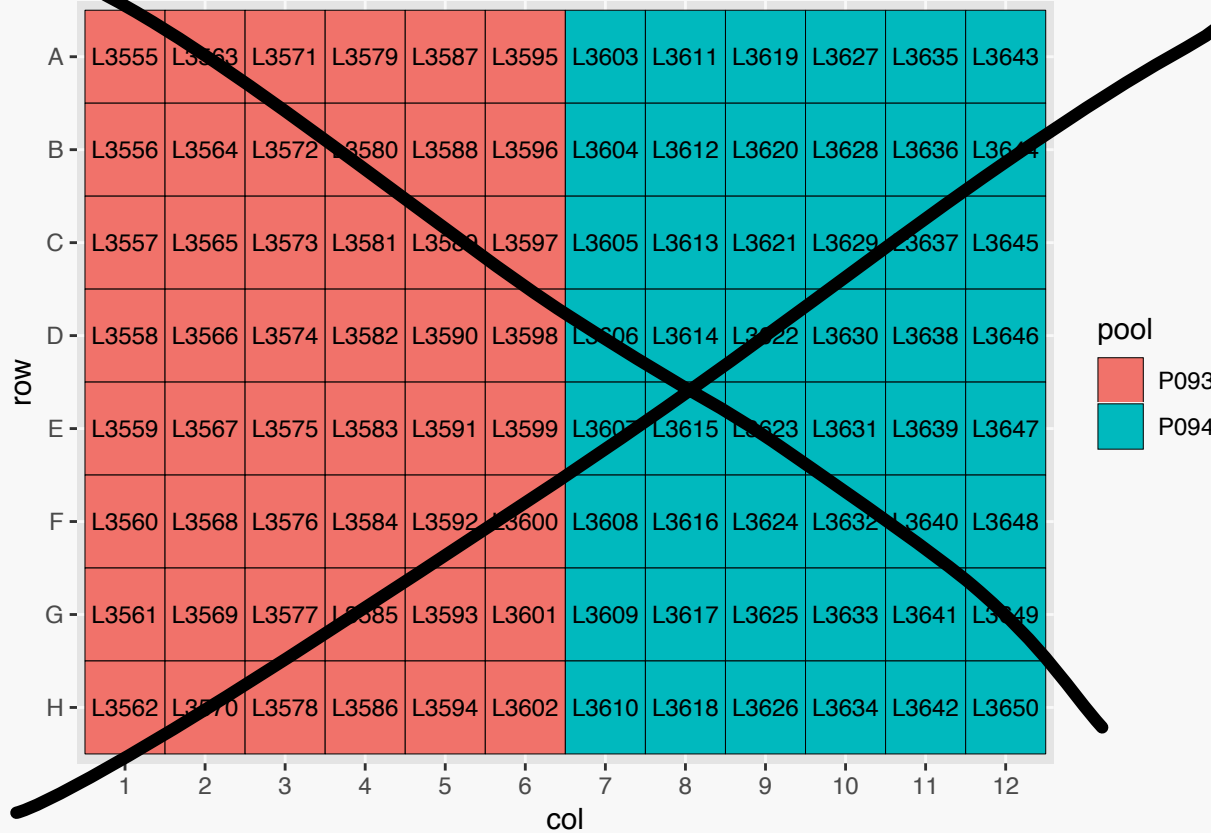
Annotation Summary

1 annotation by Michelle Stuart



- Pull up the csv in excel (from the actual drive you used on the robot with any real time changes made) and pare down the columns to the ones that will go into the database.

Generate plate maps



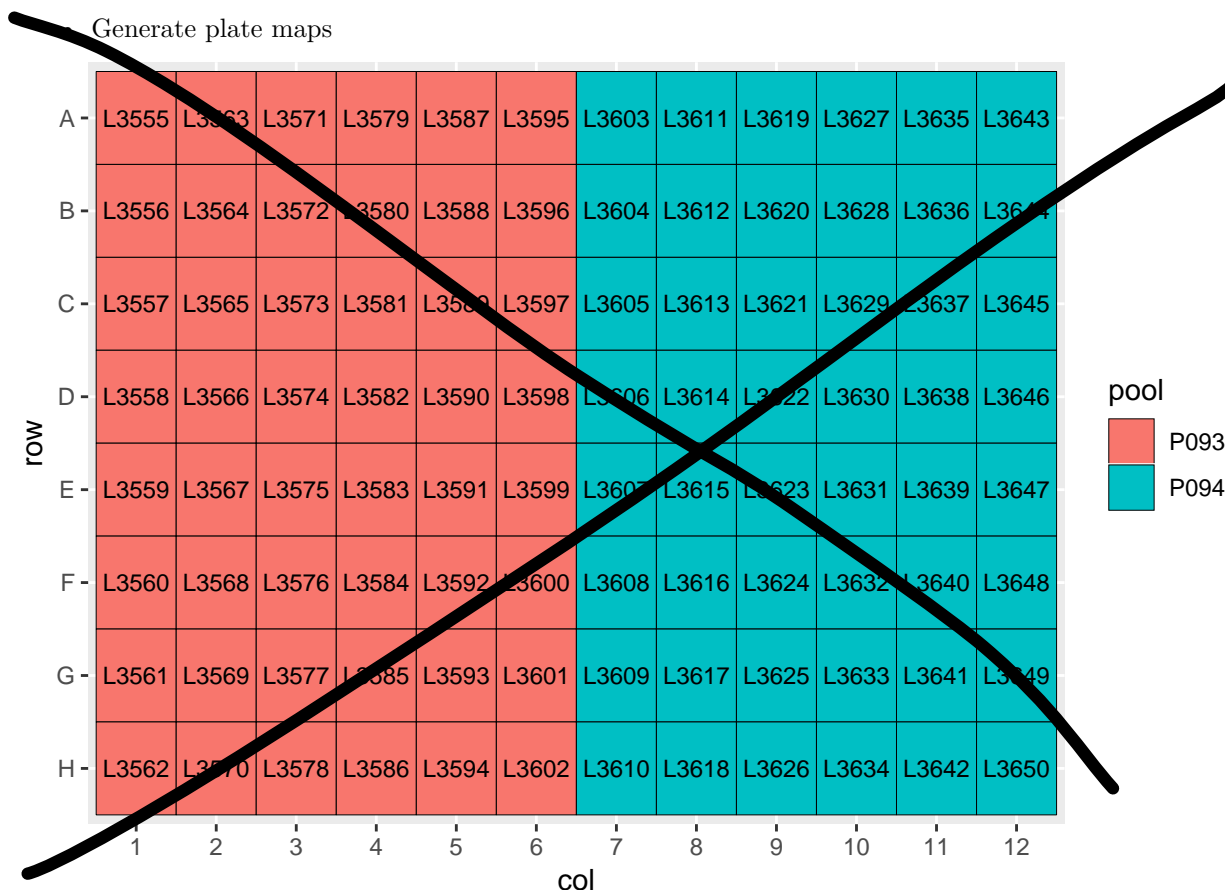
Look at the notes made on the iPad:

Post-robot quality control 2018-08-07

For the plates that were put together on the robot on 8/3/2018 and 8/6/2018, the script to generate the robot plans was run several times in order to accommodate software glitches with the robot (it didn't want to go to some destination plate locations, sometimes P12, sometimes P9). Because of this, all of the rows that had been added to the database had to be removed and resent to the database based on the csv's that the robot actually used.

- Spin the plate down and examine the wells:
- less volume in G11, H11
- Pull up the csv in excel (from the actual drive you used on the robot with any real time changes made) and pare down the columns to the ones that will go into the database.

Generate plate maps



Look at the notes made on the iPad:

“Because it looked like some samples didn't get water in Round 4, changed the method to go down to 1mm from bottom to aspirate. There as been H2O in the pipets when I have looked.”

- Write the lines to the database

```
## [1] TRUE
```

```
## [1] TRUE
```