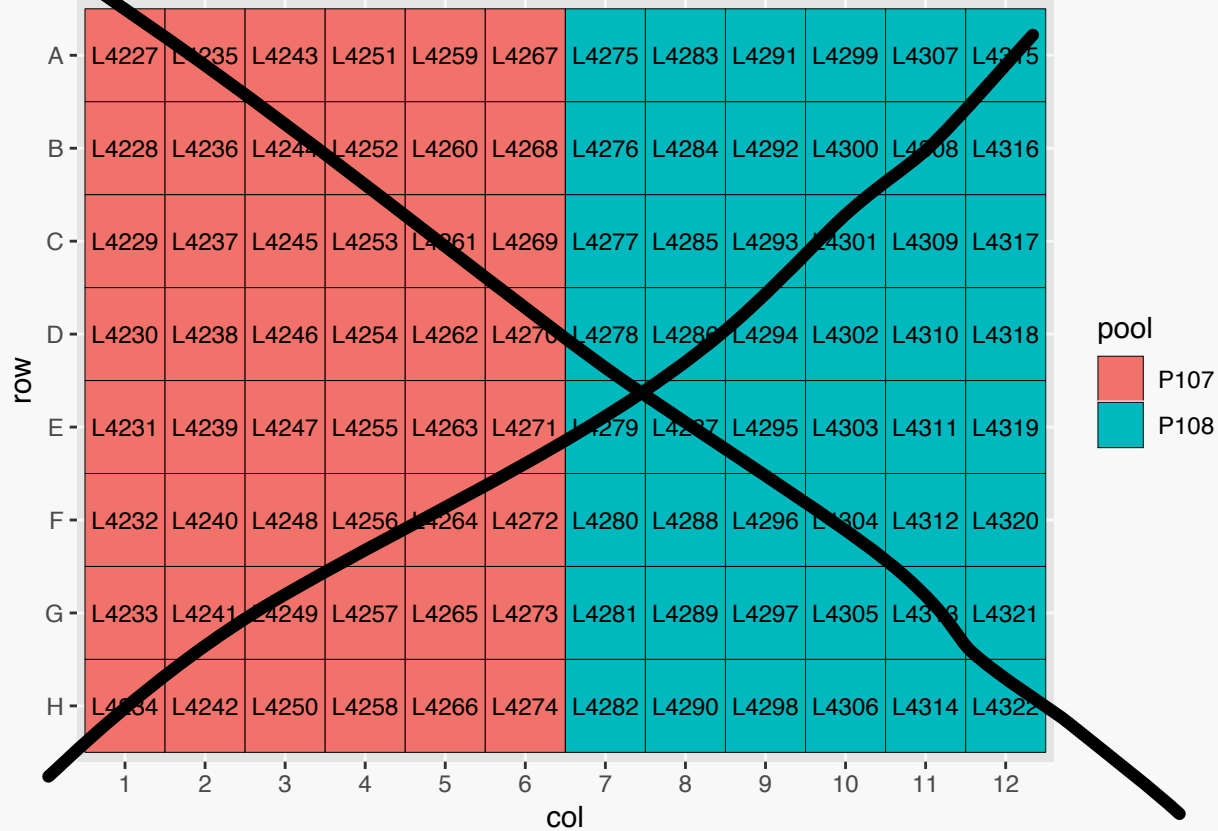- Pull up the csv in excel (from the actual drive you used on the robot with any real time changes made) and pare down the columns to the ones that will go into the database.
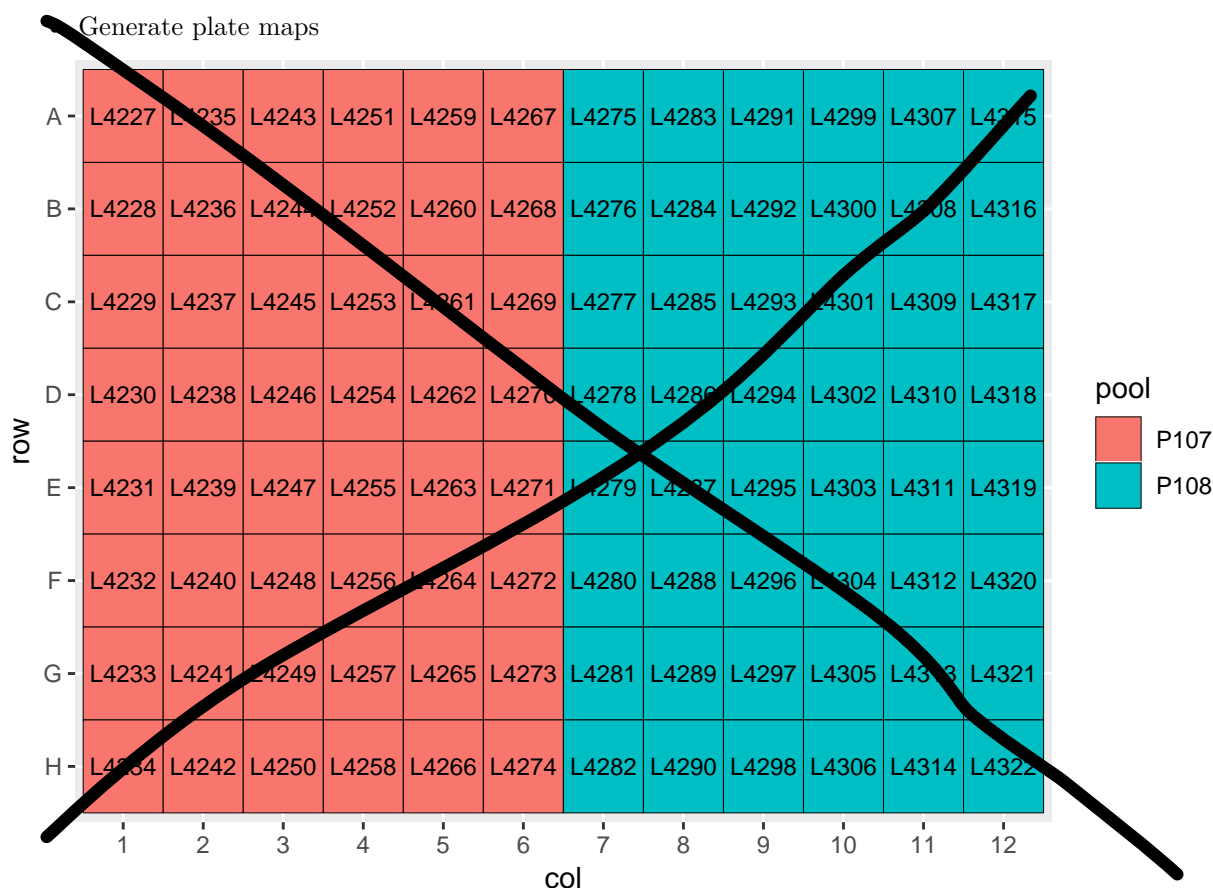
Generate plate maps

	1	2	3	4	5	6	7	8	9	10	11	12
A	L4227	L4235	L4243	L4251	L4259	L4267	L4275	L4283	L4291	L4299	L4307	L4315
B	L4228	L4236	L4244	L4252	L4260	L4268	L4276	L4284	L4292	L4300	L4308	L4316
C	L4229	L4237	L4245	L4253	L4261	L4269	L4277	L4285	L4293	L4301	L4309	L4317
D	L4230	L4238	L4246	L4254	L4262	L4270	L4278	L4286	L4294	L4302	L4310	L4318
E	L4231	L4239	L4247	L4255	L4263	L4271	L4279	L4287	L4295	L4303	L4311	L4319
F	L4232	L4240	L4248	L4256	L4264	L4272	L4280	L4288	L4296	L4304	L4312	L4320
G	L4233	L4241	L4249	L4257	L4265	L4273	L4281	L4289	L4297	L4305	L4313	L4321
H	L4234	L4242	L4250	L4258	L4266	L4274	L4282	L4290	L4298	L4306	L4314	L4322

row / col

pool

- P107
- P108

- Look at the notes made on the iPad:

Post-robot quality control 2018-08-07

For the plates that were put together on the robot on 8/3/2018 and 8/6/2018, the script to generate the robot plans was run several times in order to accomodate software glitches with the robot (it didn't want to go to some destination plate locations, sometimes P12, sometimes P9). Because of this, all of the rows that had been added to the database had to be removed and resent to the database based on the csv's that the robot actually used.

- Spin the plate down and examine the wells:

- everything looks good

- Pull up the csv in excel (from the actual drive you used on the robot with any real time changes made) and pare down the columns to the ones that will go into the database.

- Generate plate maps

- Look at the notes made on the iPad:

- no notes

- Write the lines to the database

```
## [1] TRUE
```

```
## [1] TRUE
```