

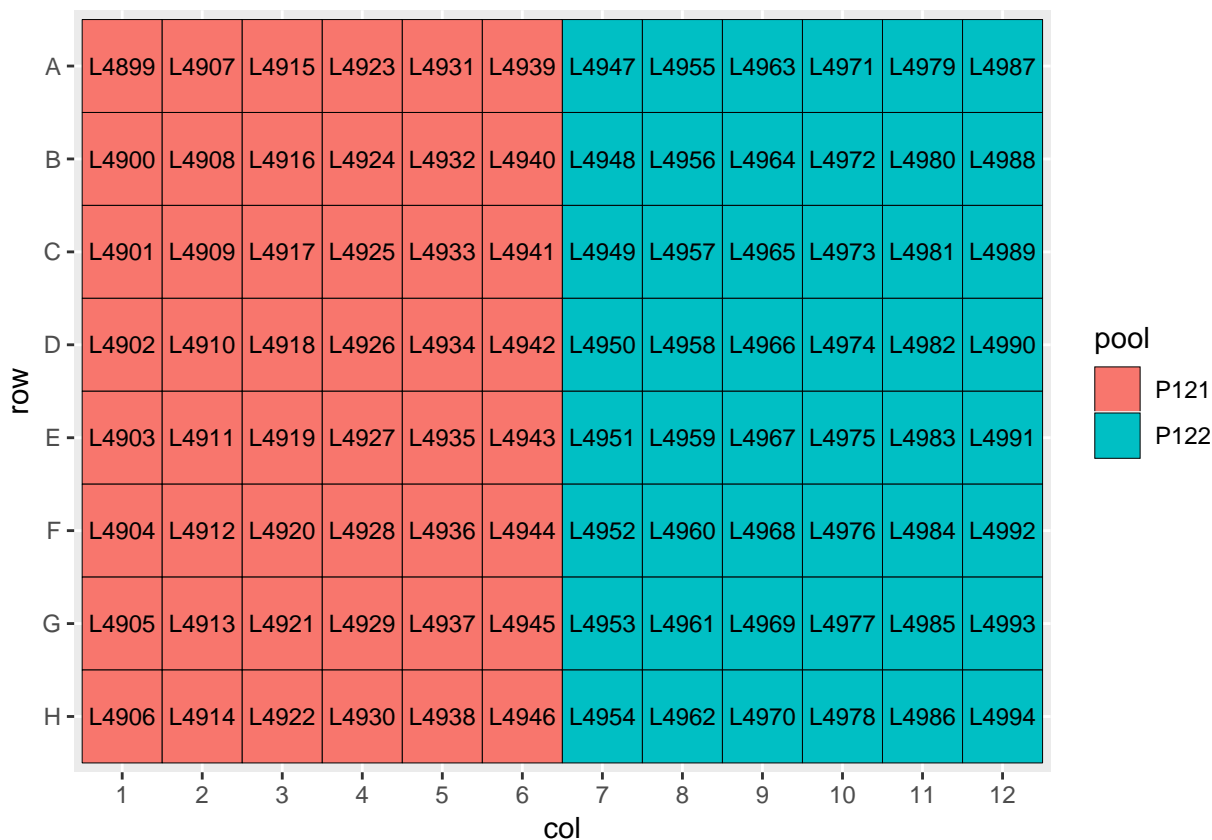
# Post-robot quality control 2018-08-07

For the plates that were put together on the robot on 8/3/2018 and 8/6/2018, the script to generate the robot plans was run several times in order to accommodate software glitches with the robot (it didn't want to go to some destination plate locations, sometimes P12, sometimes P9). Because of this, all of the rows that had been added to the database had to be removed and resent to the database based on the csv's that the robot actually used.

- Spin the plate down and examine the wells:

Everything looks good

- Pull up the csv in excel (from the actual drive you used on the robot with any real time changes made) and pare down the columns to the ones that will go into the database.
- Generate plate maps



- Look at the notes made on the iPad: “More efficient to load all digests for digest plate (dig plate up once, multi dest plates)?”
- Write the lines to the database

```
## [1] TRUE
```

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